



**zenon**  
by COPA-DATA

# zenon driver manual

## BACnet32

v.8.10



**COPA-DATA**

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# 1 Welcome to COPA-DATA help

## ZENON VIDEO-TUTORIALS

You can find practical examples for project configuration with zenon in our YouTube channel ([https://www.copadata.com/tutorial\\_menu](https://www.copadata.com/tutorial_menu)). The tutorials are grouped according to topics and give an initial insight into working with different zenon modules. All tutorials are available in English.

## GENERAL HELP

If you cannot find any information you require in this help chapter or can think of anything that you would like added, please send an email to [documentation@copadata.com](mailto:documentation@copadata.com).

## PROJECT SUPPORT

You can receive support for any real project you may have from our Support Team, who you can contact via email at [support@copadata.com](mailto:support@copadata.com).

## LICENSES AND MODULES

If you find that you need other modules or licenses, our staff will be happy to help you. Email [sales@copadata.com](mailto:sales@copadata.com).

# 2 BACnet32

The BACnet driver is used for communication between one or more devices supporting BACnet (BACnet automation stations) and the zenon Runtime. This requires that the connected BACnet devices run as servers. Only client functionality is implemented in the driver.

### 3 BACnet32 - data sheet

General:	
Driver file name	BACnet32.exe
Driver name	Bacnet und DDC4000 Treiber
PLC types	All Bacnet "BACnet over IP, Annex J" compliant PLCs; Kieback + Peter DDC4000 controllers
PLC manufacturer	Kieback + Peter; BACnet

Driver supports:	
Protocol	BACnet/IP
Addressing: Address-based	Name based
Addressing: Name-based	--
Spontaneous communication	X
Polling communication	X
Online browsing	X
Offline browsing	--
Real-time capable	X
Blockwrite	--
Modem capable	--
RDA numerical	--
RDA String	--
Hysteresis	--
extended API	--
Supports status bit <b>WR-SUC</b>	--
alternative IP address	--

Requirements:	
Hardware PC	Standard network card
Software PC	WinPcap.dll
Hardware PLC	--
Software PLC	--
Requires v-dll	X

Platforms:	
Operating systems	Windows 10; Windows 7; Windows 8; Windows 8.1; Windows Server 2008 R2; Windows Server 2012; Windows Server 2012 R2; Windows Server 2016

## 4 Driver history

Date	Driver version	Change
07.07.08	3600	Created driver documentation
10/27/2008	3800	New functionality: configurable priority and read delay
11/17/2008	4000	Corrected errors in documentation links

### DRIVER VERSIONING

The versioning of the drivers was changed with zenon 7.10. There is a cross-version build number as of this version. This is the number in the 4th position of the file version,  
For example: **7.10.0.4228** means: The driver is for version **7.10** service pack **0**, and has the build number **4228**.

Expansions or error rectifications will be incorporated into a build in the future and are then available from the next consecutive build number.

### Example

A driver extension was implemented in build **4228**. The driver that you are using is build number **8322**. Because the build number of your driver is higher than the build number of the extension, the extension is included. The version number of the driver (the first three digits of the file version) do not have any significance in relation to this. The drivers are version-agnostic

## 5 Requirements

This chapter contains information on the requirements that are necessary for use of this driver.

### 5.1 PC

Driver files: Copy BACnet32.exe, PTP.dll, nb\_link\_settings.dll to the program directory, if they are not already there.

WinPcap.dll; installation set available for free in the Internet, e.g. at <http://www.winpcap.org/install/default.htm>

Copy the file WinPcap.dll to the directory system32.

We recommend version 3.0 or higher.

## 6 Configuration

In this chapter you will learn how to use the driver in a project and which settings you can change.

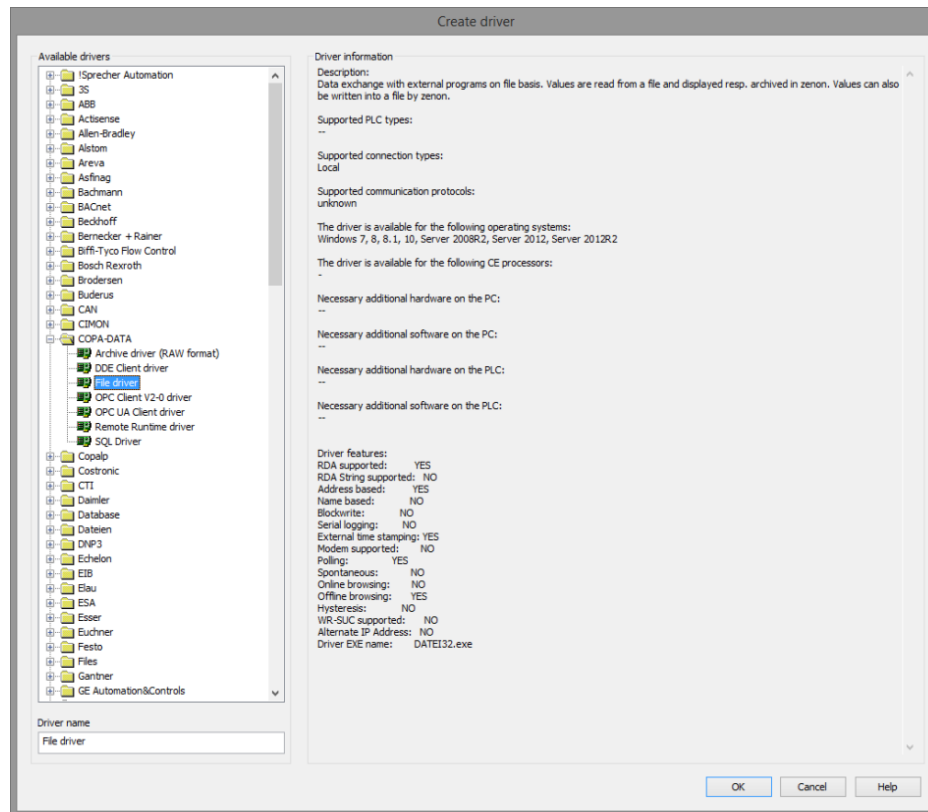
### Information

Find out more about further settings for zenon variables in the chapter Variables (main.chm::/15247.htm) of the online manual.



## 6.1 Creating a driver

In the **Create driver** dialog, you create a list of the new drivers that you want to create.



Parameter	Description
<b>Available drivers</b>	<p>List of all available drivers.</p> <p>The display is in a tree structure:  [+] expands the folder structure and shows the drivers contained therein.  [-] reduces the folder structure</p> <p>Default: <i>no selection</i></p>
<b>Driver name</b>	<p>Unique <b>Identification</b> of the driver.</p> <p>Default: <i>Empty</i></p> <p>The input field is pre-filled with the pre-defined <b>Identification</b> after selecting a driver from the list of available drivers.</p>
<b>Driver information</b>	<p>Further information on the selected driver.</p> <p>Default: <i>Empty</i></p> <p>The information on the selected driver is shown in this area after selecting a driver.</p>

## CLOSE DIALOG

Option	Description
OK	Accepts all settings and opens the driver configuration dialog of the selected driver.
Cancel	Discards all changes and closes the dialog.
Help	Opens online help.



### Information

The content of this dialog is saved in the file called Treiber\_[Language].xml. You can find this file in the following folder:

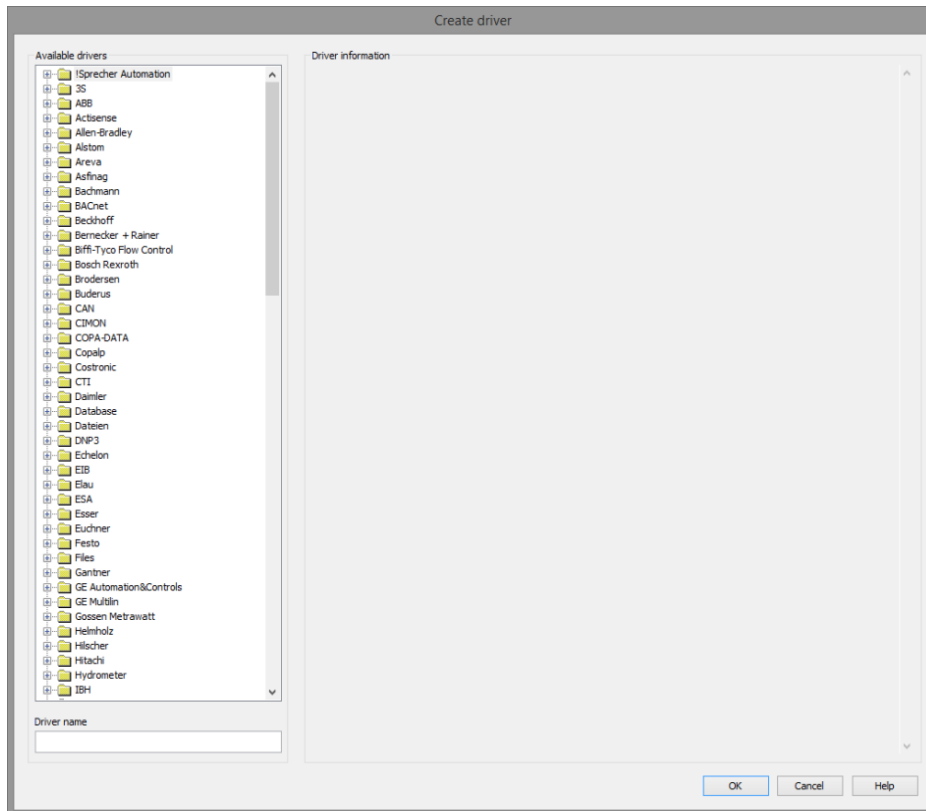
*C:\ProgramData\COPA-DATA\zenon[version number].*

## CREATE NEW DRIVER

In order to create a new driver:

1. Right-click on **Driver** in the Project Manager and select **New driver** in the context menu.  
Optional: Select the **New driver** button from the toolbar of the detail view of the **Variables**.  
The **Create driver** dialog is opened.

- The dialog offers a list of all available drivers.

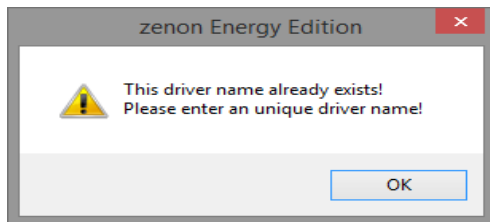


- Select the desired driver and name it in the **Driver name** input field.  
This input field corresponds to the **Identification** property. The name of the selected driver is automatically inserted into this input field by default.  
The following is applicable for the **Driver name**:
  - ▶ The **Driver name** must be unique.  
If a driver is used more than once in a project, a new name has to be given each time.  
This is evaluated by clicking on the **OK** button. If the driver is already present in the project, this is shown with a warning dialog.
  - ▶ The **Driver name** is part of the file name.  
Therefore it may only contain characters which are supported by the operating system.  
Invalid characters are replaced by an underscore (\_).
  - ▶ **Attention:** This name cannot be changed later on.
- Confirm the dialog by clicking on the **OK** button.  
The configuration dialog for the selected driver is opened.

**Note:** The language of driver names cannot be switched. They are always shown in the language in which they have been created, regardless of the language of the Editor. This also applies to driver object types.

### DRIVER NAME DIALOG ALREADY EXISTS

If there is already a driver in the project, this is shown in a dialog. The warning dialog is closed by clicking on the **OK** button. The driver can be named correctly.



### ZENON PROJECT

The following drivers are created automatically for newly-created projects:

- ▶ **Intern**
- ▶ **MathDr32**
- ▶ **SysDrv**



#### **Information**

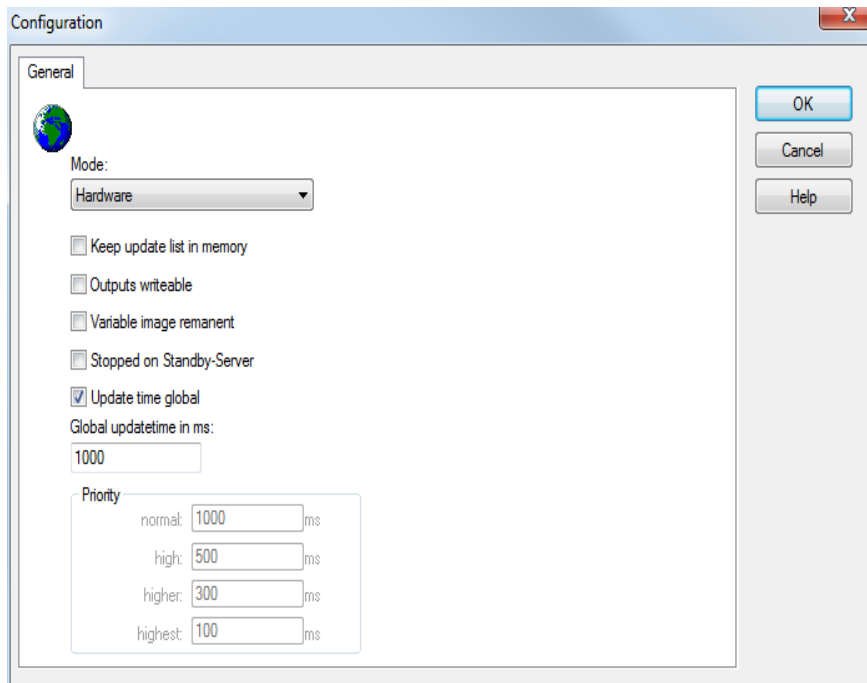
Only the required drivers need to be present in a zenon project. Drivers can be added at a later time if required.

## 6.2 Settings in the driver dialog

You can change the following settings of the driver:

## 6.2.1 General

The configuration dialog is opened when a driver is created. In order to be able to open the dialog later for editing, double click on the driver in the list or click on the **Configuration** property.



Option	Description
<b>Mode</b>	<p>Allows to switch between hardware mode and simulation mode</p> <ul style="list-style-type: none"> <li>▶ <i>Hardware:</i> A connection to the control is established.</li> <li>▶ <i>Simulation - static:</i> No communication between to the control is established, the values are simulated by the driver. In this modus the values remain constant or the variables keep the values which were set by zenon Logic. Each variable has its own memory area. E.g. two variables of the type marker with offset 79 can have different values in the Runtime and do not influence each other. Exception: The simulator driver.</li> <li>▶ <i>Simulation - counting:</i> No communication between to the control is established, the values are simulated by the driver. In this modus the driver increments the values</li> </ul>

Option	Description
	<p>within a value range automatically.</p> <ul style="list-style-type: none"> <li>▶ <i>Simulation - programmed:</i> No communication is established to the PLC. The values are calculated by a freely programmable simulation project. The simulation project is created with the help of the zenon Logic Workbench and runs in a zenon Logic Runtime which is integrated in the driver. For details see chapter Driver simulation (main.chm::/25206.htm).</li> </ul>
<b>Keep update list in the memory</b>	<p>Variables which were requested once are still requested from the control even if they are currently not needed. This has the advantage that e.g. multiple screen switches after the screen was opened for the first time are executed faster because the variables need not be requested again. The disadvantage is a higher load for the communication to the control.</p>
<b>Output can be written</b>	<ul style="list-style-type: none"> <li>▶ <i>Active:</i> Outputs can be written.</li> <li>▶ <i>Inactive:</i> Writing of outputs is prevented.</li> </ul> <p><b>Note:</b> Not available for every driver.</p>
<b>Variable image remanent</b>	<p>This option saves and restores the current value, time stamp and the states of a data point.</p> <p>Fundamental requirement: The variable must have a valid value and time stamp.</p> <p>The variable image is saved in hardware mode if one of these statuses is active:</p> <ul style="list-style-type: none"> <li>▶ User status <i>M1 (0)</i> to <i>M8 (7)</i></li> <li>▶ <i>REVISION(9)</i></li> <li>▶ <i>AUS(20)</i></li> <li>▶ <i>ERSATZWERT(27)</i></li> </ul> <p>The variable image is always saved if:</p> <ul style="list-style-type: none"> <li>▶ the variable is of the object type <b>Driver variable</b></li> <li>▶ the driver runs in simulation mode. (not</li> </ul>

Option	Description
	<p>programmed simulation)</p> <p>The following states are not restored at the start of the Runtime:</p> <ul style="list-style-type: none"> <li>▶ <i>SELECT(8)</i></li> <li>▶ <i>WR-ACK(40)</i></li> <li>▶ <i>WR-SUC(41)</i></li> </ul> <p>The mode <b>Simulation - programmed</b> at the driver start is not a criterion in order to restore the remanent variable image.</p>
<b>Stop on Standby Server</b>	<p>Setting for redundancy at drivers which allow only one communication connection. For this the driver is stopped at the Standby Server and only started at the upgrade.</p> <p><b>Attention:</b> If this option is active, the gapless archiving is no longer guaranteed.</p> <ul style="list-style-type: none"> <li>▶ <i>Active:</i> Sets the driver at the not-process-leading Server automatically in a stop-like state. In contrast to stopping via driver command, the variable does not receive status <b>switched off</b> (<b>statusverarbeitung.chm::/24150.htm</b>) but an empty value. This prevents that at the upgrade to the Server irrelevant values are created in the AML, CEL and Historian.</li> </ul> <p>Default: <i>inactive</i></p> <p><b>Note:</b> Not available if the CE terminal serves as a data server. You can find further information in the zenon Operator manual in the CE terminal as a data server chapter.</p>
<b>Global Update time</b>	<p>Setting for the global update times in milliseconds:</p> <ul style="list-style-type: none"> <li>▶ <i>Active:</i> The set <b>Global update time</b> is used for all variables in the project. The priority set at the variables is not used.</li> <li>▶ <i>Inactive:</i> The set priorities are used for the individual variables.</li> </ul>

Option	Description
	<b>Exceptions:</b> Spontaneous drivers ignore this option. They generally use the shortest possible update time. For details, see the <b>Spontaneous driver update time</b> section.
<b>Priority</b>	<p>The polling times for the individual priority classes are set here. All variables with the according priority are polled in the set time.</p> <p>The variables are allocated separately in the settings of the variable properties.</p> <p>The communication of the individual variables can be graded according to importance or required topicality using the priority classes. Thus the communication load is distributed better.</p> <p><b>Attention:</b> Priority classes are not supported by each driver, e.g. spontaneously communicating zenon drivers.</p>

#### CLOSE DIALOG

Option	Description
<b>OK</b>	<b>Applies all changes in all tabs and closes the dialog.</b>
<b>Cancel</b>	Discards all changes in all tabs and closes the dialog.
<b>Help</b>	Opens online help.

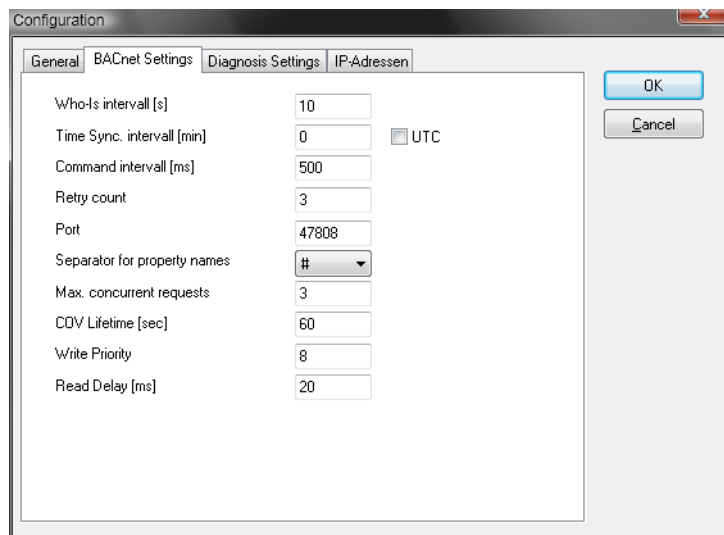
#### UPDATE TIME FOR SPONTANEOUS DRIVERS

With spontaneous drivers, for **Set value**, **advising** of variables and **Requests**, a read cycle is triggered immediately - regardless of the set update time. This ensures that the value is immediately available for visualization after writing. The update time is generally 100 ms.

Spontaneous drivers are **ArchDrv**, **BiffiDCM**, **BrTcp32**, **DNP3**, **Esser32**, **FipDrv32**, **FpcDrv32**, **IEC850**, **IEC870**, **IEC870\_103**, **Otis**, **RTK9000**, **S7DCOS**, **SAIA\_Slave**, **STRATON32** and **Trend32**.



## 6.2.2 Driver dialog BACnet settings



Configuration dialog box, BACnet Settings tab. The dialog contains the following parameters and values:

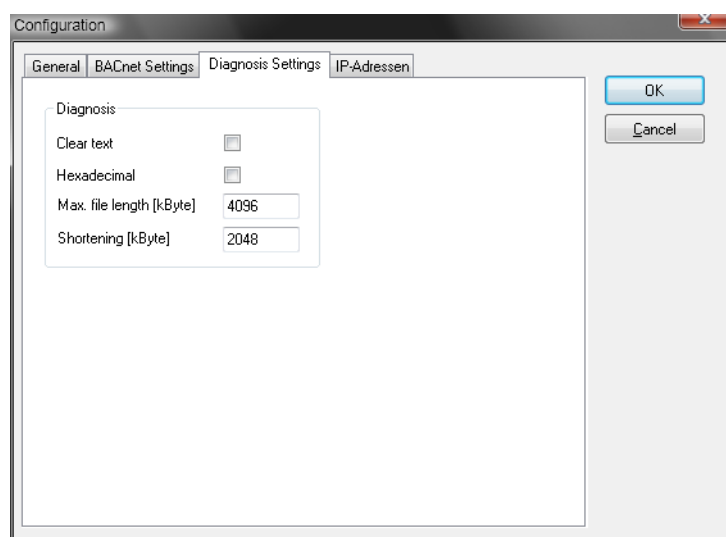
Parameter	Value
Who-Is interval [s]	10
Time Sync. interval [min]	0
Command interval [ms]	500
Retry count	3
Port	47808
Separator for property names	#
Max. concurrent requests	3
COV Lifetime [sec]	60
Write Priority	8
Read Delay [ms]	20

The 'UTC' checkbox is checked. The dialog has 'OK' and 'Cancel' buttons.

Parameter	Description
<b>Who-Is cycle [s]</b>	Cycle time for sending the "Who-Is" service
<b>Time synchronization cycle [min]</b>	Cycle time for time synchronization [min], Default: 0 (no synchronization)
<b>Command output time [ms]</b>	Command output time for sending strategy 1 (pulse command) [ms]
<b>Number of retries</b>	max. number for sending out the "Who-Has" service per object
<b>Port</b>	Configuration of the UDP port in the decimal format. (Default for BACNet: 47808)
<b>Separator for property names</b>	
<b>Number of simultaneous queries</b>	Maximum number of simultaneous COV subscription packets. Used for BACNet devices that can only buffer and process a certain number of packets.
<b>COV lifetime [sec]</b>	After this time, registered COV subscriptions will become invalid and will then be requested from the driver again (see BACnet standard).
<b>Write priority</b>	Defines the write priority for variables. (see BACnet standard). The lower the value, the higher the priority ATTENTION: Values under "8" are often used by the PLC itself and should therefore be used with caution.

Parameter	Description
<b>Read delay [ms]</b>	Configurable delay between 2 polling queries. This is required for devices with performance problems.

### 6.2.3 Driver dialog diagnosis settings



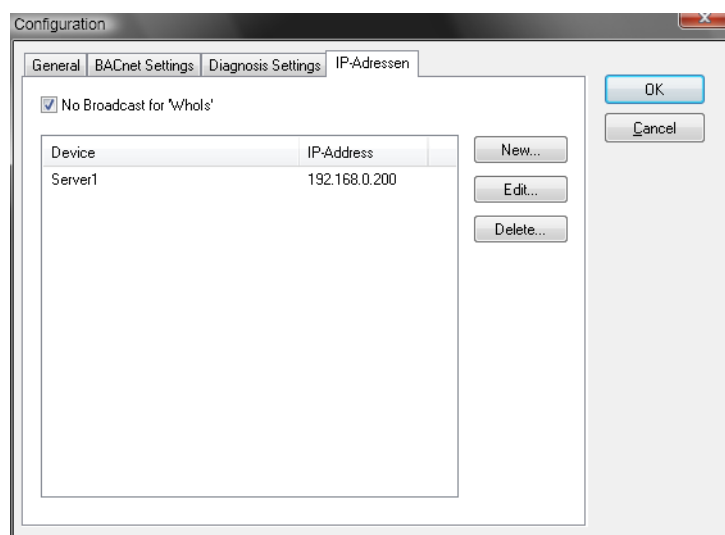
Parameters	Description
<b>Plain text</b>	Logging of the BACnet telegram in plain text
<b>Hex format</b>	Logging of the BACnet telegram in hexadecimal format
<b>Max file size [kByte]</b>	Max. size of the log file
<b>Shortening [kByte]</b>	Shortening of the log file, if max. file length is reached

Data is stored in the file <runtimepath>\RT\FILES\zenon\custom\drivers\BACnet.log

For Editor communication (browsing), the following file is used:

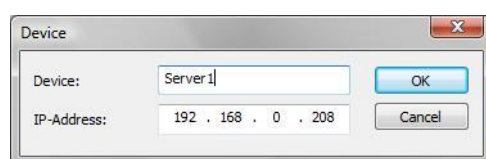
<SQLpath>\<ProjektGUID>\FILES\zenon\custom\drivers\BACnet.log.

## 6.2.4 Driver dialog IP addresses



Parameters	Description
<b>No broadcast for 'Whols'</b>	<p>If this option is active, 'Whols' messages will only be sent to the BACNet stations in the list below.</p> <p>ATTENTION: This function is not a part of the BACNet standard. We cannot guarantee that it works with all BACNet PLCs.</p>
<b>New...</b>	<p>Create a new station:</p> <p>Device: Specify the device name (e.g. device name in BACNet)</p> <p>IP address: IP address of the target device</p>
<b>Edit...</b>	Edits the selected address
<b>Delete...</b>	Deletes the selected address

### DIALOG FOR CREATING AND MODIFYING CONNECTIONS



Device	Freely definable name of the connection
IP address	IP address of the BACnet device

## 7 Creating variables

This is how you can create variables in the zenon Editor:

### 7.1 Creating variables in the Editor

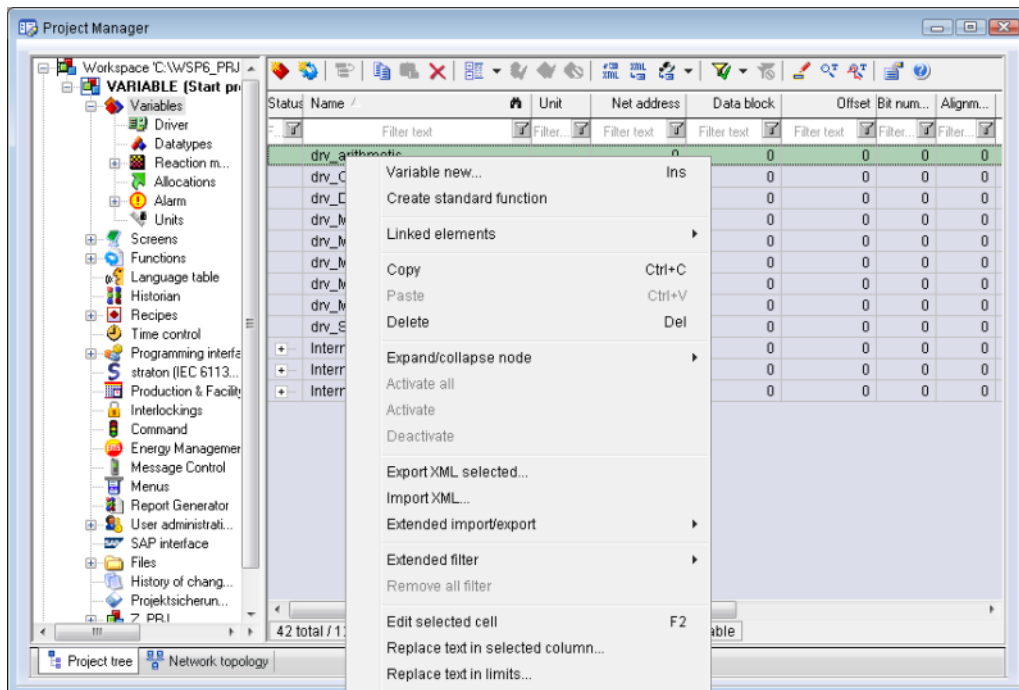
Variables can be created:

- ▶ as simple variables
- ▶ in arrays (main.chm::/15262.htm)
- ▶ as structure variables (main.chm::/15278.htm)

#### VARIABLE DIALOG

To create a new variable, regardless of which type:

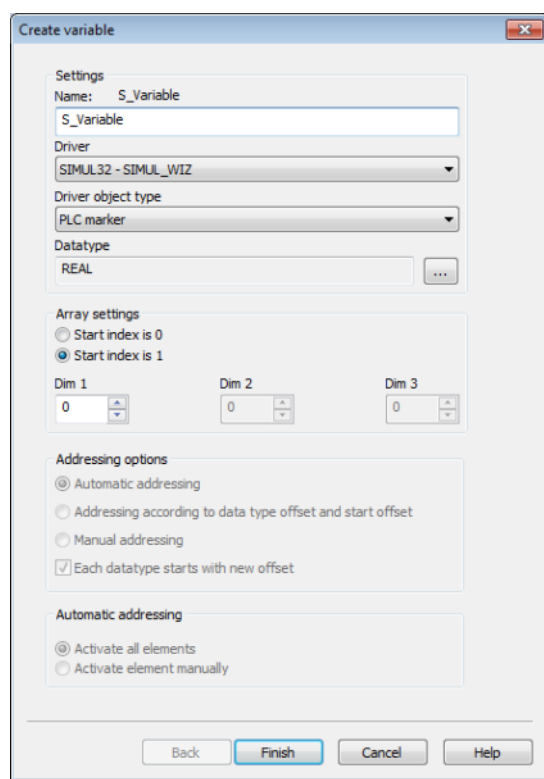
1. Select the **New variable** command in the **Variables** node in the context menu



The dialog for configuring variables is opened

2. Configure the variable
3. The settings that are possible depends on the type of variables

## CREATE VARIABLE DIALOG



Property	Description
<b>Name</b>	<p>Distinct name of the variable. If a variable with the same name already exists in the project, no additional variable can be created with this name.</p> <p>Maximum length: 128 characters</p> <p><b>Attention:</b> the characters # and @ are not permitted in variable names. If non-permitted characters are used, creation of variables cannot be completed and the <b>Finish</b> button remains inactive.</p> <p><b>Note:</b> For some drivers, the addressing is possible over the property <b>Symbolic address</b>, as well.</p>
<b>Drivers</b>	<p>Select the desired driver from the drop-down list.</p> <p><b>Note:</b> If no driver has been opened in the project, the driver for internal variables (<b>Intern.exe (Main.chm::/Intern.chm::/Intern.htm)</b>) is automatically loaded.</p>
<b>Driver Object Type</b> (cti.chm::/28685.htm)	Select the appropriate driver object type from the drop-down list.
<b>Data Type</b>	Select the desired data type. Click on the ... button to open the

Property	Description
	selection dialog.
<b>Array settings</b>	Expanded settings for array variables. You can find details in the Arrays chapter.
<b>Addressing options</b>	Expanded settings for arrays and structure variables. You can find details in the respective section.
<b>Automatic addressing</b>	Expanded settings for arrays and structure variables. You can find details in the respective section.

## SYMBOLIC ADDRESS

The **Symbolic address** property can be used for addressing as an alternative to the **Name** or **Identification** of the variables. Selection is made in the driver dialog; configuration is carried out in the variable property. When importing variables of supported drivers, the property is entered automatically.

Maximum length: 1024 characters.

The following drivers support the **Symbolic address**:

- ▶ 3S\_V3
- ▶ AzureDrv
- ▶ BACnetNG
- ▶ IEC850
- ▶ KabaDPsServer
- ▶ OPCUA32
- ▶ Phoenix32
- ▶ POZYTON
- ▶ RemoteRT
- ▶ S7TIA
- ▶ SEL
- ▶ SnmpNg32
- ▶ PA\_Drv

## INHERITANCE FROM DATA TYPE

**Measuring range**, **Signal range** and **Set value** are always:

- ▶ derived from the datatype
- ▶ Automatically adapted if the data type is changed

**Note for signal range:** If a change is made to a data type that does not support the set **signal range**, the **signal range** is amended automatically. For example, for a change from **INT** to **SINT**, the **signal range** is changed to 127. The amendment is also carried out if the **signal range** was not inherited from the data type. In this case, the **measuring range** must be adapted manually.

## 7.2 Addressing

Addressing the variables of the BACnet driver is done with the unique names of the variables. The datapoints of the BACnet driver are uniquely referenced by the object names. The object name of the device object is placed before the object name of the BACnet object; the names are separated by a dot (e.g. BPS10.d10a002); for schedule objects, the name of the property is attached, again separated by a dot. The virtual datapoints of the type BACnet component status represent the status of the connection. They are uniquely identified by the object name of the device object.

### SETTINGS FOR THE UNIQUE ADDRESSING OF VARIABLES

Property	Description
<b>Name</b>	Used for the unique addressing. Format: <b>device-name.object-name[.property]</b>
<b>Identification</b>	Freely definable identification. E.g. for Resources label, comments, ... Can be used for unique addressing. Format: <b>device-name.object-name[.property]</b>
<b>Net address</b>	not used for this driver
<b>Data block</b>	not used for this driver
<b>Offset</b>	not used for this driver
<b>Alignment</b>	not used for this driver
<b>Bit number</b>	not used for this driver
<b>String length</b>	Only available for String variables. Maximum number of characters that the variable can take.
<b>Driver connection/Driver Object Type</b>	Object type of the variables. Depending on the driver used, is selected when the variable is created and can be changed here.
<b>Driver connection/Data Type</b>	Data type of the variable. Is selected during the creation of the variable; the type can be changed here.  <b>Attention:</b> If you change the data type later, all other properties of the

Property	Description
	variable must be checked and adjusted, if necessary.
<b>Driver connection/Priority</b>	Assigns a variable a priority for the update time.

## 7.3 Driver objects and datatypes

Driver objects are areas available in the PLC, such as markers, data blocks etc. Here you can find out which driver objects are provided by the driver and which IEC data types can be assigned to the respective driver objects.

### 7.3.1 Driver objects

The following object types are available in this driver:

Driver Object Type	Channel type	Read	Write	Supported data types	Comment
<b>Output</b>	11	X	X	<i>BOOL, REAL, SINT, USINT</i>	
<b>Input</b>	10	X	X	<i>BOOL, REAL, SINT, USINT</i>	
<b>PLC marker</b>	8	X	X	<i>BOOL, REAL, SINT, USINT</i>	
<i>Communication details</i>	35	X	X	<i>BOOL, SINT, USINT, INT, UINT, DINT, UDINT, REAL, STRING</i>	<p>Variables for the static analysis of the communication; is transferred between driver and Runtime (not to the PLC).</p> <p><b>Note:</b> The addressing and the behavior is the same for most zenon drivers.</p> <p>You can find detailed information on this in</p>



Driver Object Type	Channel type	Read	Write	Supported data types	Comment
					the Communication details (Driver variables) (on page 35) chapter.

**Key:**

X: supported

--: not supported

### DRIVER OBJECT TYPES AND SUPPORTED IEC DATA TYPES FOR PROCESS VARIABLES IN ZENON

Driver object types	Supported datatypes	Read	Write	BACnet Object Type
<b>Input</b>	<i>BOOL</i>	X	--	Binary Input
	<i>REAL</i>	X	--	Analog Input
	<i>SINT, USINT</i>	X	--	Multistate Input
<b>Output</b>	<i>BOOL</i>	--	X	Binary Output
	<i>REAL</i>	--	X	Analog Output
	<i>SINT, USINT</i>	--	X	Multistate Output
<b>PLC marker</b>	<i>BOOL</i>	X	X	Binary Value
	<i>REAL</i>	X	X	Analog Value Schedule - Present Value
	<i>USINT</i>	X	X	Component status
	<i>STRING *</i>	X	X	Schedule - Effective Period Schedule - Weekly Schedule Schedule - Exception Schedule

\* The individual properties of schedule objects have a complex and variable structure (See BACnet standard). That is why you can only hand them over as Strings to zenon. Depending on the property, these Strings have different formats (you can leave out spaces when setting values):

### EFFECTIVE PERIOD

Parameter	Description
<b>Effective Period:</b>	<Start date> - <End date> }
Date:	<Year – 1900>.<Month (1..12)>.<Day (1..31)>.<Weekday (1..7, 1 = Monday)>

### WEEKLY SCHEDULE

Parameter	Description																								
<b>Weekly Schedule:</b>	{ Array [1..7] of <Daily Schedule> }																								
<b>Daily Schedule:</b>	{ List of <Time Value> }																								
<b>Time Value:</b>	<Time>, [<Type>] <Value> }																								
<b>Time:</b>	<Hour>:<Minute>:<Second>:<1/100 sec.>																								
<b>Type:</b>	<table> <tr><td>1</td><td>BOOLEAN</td></tr> <tr><td>2</td><td>UNSIGNED</td></tr> <tr><td>3</td><td>SIGNED</td></tr> <tr><td>4</td><td>REAL</td></tr> <tr><td>5</td><td>DOUBLE</td></tr> <tr><td>6</td><td>OCTET_STRING</td></tr> <tr><td>7</td><td>CHARACTER_STRING</td></tr> <tr><td>8</td><td>BIT_STRING</td></tr> <tr><td>9</td><td>ENUMERATED</td></tr> <tr><td>10</td><td>DATE</td></tr> <tr><td>11</td><td>TIME</td></tr> <tr><td>12</td><td>OBJECT_IDENTIFIER</td></tr> </table>	1	BOOLEAN	2	UNSIGNED	3	SIGNED	4	REAL	5	DOUBLE	6	OCTET_STRING	7	CHARACTER_STRING	8	BIT_STRING	9	ENUMERATED	10	DATE	11	TIME	12	OBJECT_IDENTIFIER
1	BOOLEAN																								
2	UNSIGNED																								
3	SIGNED																								
4	REAL																								
5	DOUBLE																								
6	OCTET_STRING																								
7	CHARACTER_STRING																								
8	BIT_STRING																								
9	ENUMERATED																								
10	DATE																								
11	TIME																								
12	OBJECT_IDENTIFIER																								

## EXCEPTION SCHEDULE

Parameter	Description
<b>Exception Schedule:</b>	{ Array [1..n] of <Special Event> }
<b>Special Event:</b>	<Period> { List of <Time Value>* } <Event Priority> }
<b>Period:</b>	{ [0] <Calendar Entry> } or { [1] <Calendar Reference> }
<b>Calendar Reference:</b>	Instance no. of the referenced calendar object
<b>Calendar Entry:</b>	[0] <Date>** or [1] <Start date>** - <End date>** or [2] <WeekNDay>
<b>WeekNDay:</b>	<Month (1..12)>.<Week of month (1..6)>.<Weekday (1..7)>
<b>Event Priority:</b>	1..16, 1 = highest priority, 16 = lowest priority

\* see Weekly Schedule, \*\* see Effective Period

## 7.3.2 Mapping of the data types

All variables in zenon are derived from IEC data types. The following table compares the IEC datatypes with the datatypes of the PLC.

## EXAMPLES FOR ALL POSSIBLE IEC DATA TYPES

PLC	zenon	Range of values
<b>8 Bit signed</b>	SINT	-128 to 127
<b>8 Bit unsigned</b>	USINT	0 to 255
<b>32 bit floating point</b>	REAL	$\pm 3.4E \pm 38$
<b>Boolean</b>	BOOL	0, 1

## DATA TYPE

The term **data type** is the internal numerical identification of the data type. It is also used for the extended DBF import/export of the variables.

## 7.4 Creating variables by importing

Variables can also be imported by importing them. The XML and DBF import is available for every driver.



### Information

You can find details on the import and export of variables in the Import-Export (main.chm::/13028.htm) manual in the Variables (main.chm::/13045.htm) section.

### 7.4.1 XML import

During XML import of variables or data types, these are first assigned to a driver and then analyzed. Before import, the user decides whether and how the respective element (variable or data type) is to be imported:

- ▶ *Import:*  
The element is imported as a new element.
- ▶ *Overwrite:*  
The element is imported and overwrites a pre-existing element.
- ▶ *Do not import:*  
The element is not imported.

**Note:** The actions and their durations are shown in a progress bar during import. The import of variables is described in the following documentation. Data types are imported along the same lines.

## REQUIREMENTS

The following conditions are applicable during import:

- ▶ **Backward compatibility**  
At the XML import/export there is no backward compatibility. Data from older zenon versions can be taken over. The handover of data from newer to older versions is not supported.
- ▶ **Consistency**  
The XML file to be imported has to be consistent. There is no plausibility check on importing the file. If there are errors in the import file, this can lead to undesirable effects in the project.  
Particular attention must be paid to this, primarily if not all properties exist in the XML file and these are then filled with default values. E.g.: A binary variable has a limit value of 300.
- ▶ **Structure data types**

Structure data types must have the same number of structure elements.

Example: A structure data type in the project has 3 structure elements. A data type with the same name in the XML file has 4 structure elements. Then none of the variables based on this data type in the file are imported into the project.

#### Hint

You can find further information on XML import in the **Import - Export** manual, in the **XML import (main.chm::/13046.htm)** chapter.

## 7.4.2 DBF Import/Export

Data can be exported to and imported from dBase.

#### Information

Import and Export via CSV or dBase supported; no driver specific variable settings, such as formulas. Use export/import via XML for this.

### IMPORT DBF FILE

To start the import:

1. right-click on the variable list
2. in the drop-down list of **Extended export/import...** select the **Import dBase** command
3. follow the import assistant

The format of the file is described in the chapter File structure.

#### Information

Note:

- ▶ Driver object type and data type must be amended to the target driver in the DBF file in order for variables to be imported.
- ▶ dBase does not support structures or arrays (complex variables) at import.

### EXPORT DBF FILE

To start the export:

1. right-click on the variable list

2. in the drop-down list of **Extended export/import...** select the **Export dBase...** command
3. follow the export assistant



### Attention

DBF files:

- ▶ must correspond to the 8.3 DOS format for filenames (8 alphanumeric characters for name, 3 character suffix, no spaces)
- ▶ must not have dots (.) in the path name.  
e.g. the path *C:\users\John.Smith\test.dbf* is invalid.  
Valid: *C:\users\JohnSmith\test.dbf*
- ▶ must be stored close to the root directory in order to fulfill the limit for file name length including path: maximum 255 characters

The format of the file is described in the chapter File structure.



### Information

dBase does not support structures or arrays (complex variables) at export.

## FILE STRUCTURE OF THE DBASE EXPORT FILE

The dBaseIV file must have the following structure and contents for variable import and export:



### Attention

dBase does not support structures or arrays (complex variables) at export.

DBF files must:

- ▶ conform with their name to the 8.3 DOS format (8 alphanumeric characters for name, 3 characters for extension, no space)
- ▶ Be stored close to the root directory (Root)

## STRUCTURE

Identification	Type	Field size	Comment
KANALNAME	Char	128	Variable name.  The length can be limited using the <b>MAX_LAENGE</b> entry in the <b>project.ini</b> file.

Identification	Type	Field size	Comment
KANAL_R	C	128	<p>The original name of a variable that is to be replaced by the new name entered under "VARIABLENNAME" (variable name) (field/column must be entered manually).</p> <p>The length can be limited using the <b>MAX_LAENGE</b> entry in the <b>project.ini</b> file.</p>
KANAL_D	Log	1	The variable is deleted with the 1 entry (field/column has to be created by hand).
TAGNR	C	128	<p>Identification.</p> <p>The length can be limited using the <b>MAX_LAENGE</b> entry in the <b>project.ini</b> file.</p>
EINHEIT	C	11	Technical unit
DATENART	C	3	Data type (e.g. bit, byte, word, ...) corresponds to the data type.
KANALTYP	C	3	Memory area in the PLC (e.g. marker area, data area, ...) corresponds to the driver object type.
HWKANAL	Num	3	Net address
BAUSTEIN	N	3	Datablock address (only for variables from the data area of the PLC)
ADRESSE	N	5	Offset
BITADR	N	2	<p>For bit variables: bit address</p> <p>For byte variables: 0=lower, 8=higher byte</p> <p>For string variables: Length of string (max. 63 characters)</p>
ARRAYSIZE	N	16	<p>Number of variables in the array for index variables</p> <p>ATTENTION: Only the first variable is fully available. All others are only available for VBA or the Recipegroup Manager</p>
LES_SCHR	L	1	<p>Write-Read-Authorization</p> <p>0: Not allowed to set value.</p> <p>1: Allowed to set value.</p>
MIT_ZEIT	R	1	time stamp in zenon (only if supported by the driver)

Identification	Type	Field size	Comment
<b>OBJEKT</b>	N	2	Driver-specific ID number of the primitive object comprises TREIBER-OBJEKTYP and DATENTYP
<b>SIGMIN</b>	Float	16	Non-linearized signal - minimum (signal resolution)
<b>SIGMAX</b>	F	16	Non-linearized signal - maximum (signal resolution)
<b>ANZMIN</b>	F	16	Technical value - minimum (measuring range)
<b>ANZMAX</b>	F	16	Technical value - maximum (measuring range)
<b>ANZKOMMA</b>	N	1	Number of decimal places for the display of the values (measuring range)
<b>UPDATERATE</b>	F	19	Update rate for mathematics variables (in sec, one decimal possible) not used for all other variables
<b>MENTIEFE</b>	N	7	Only for compatibility reasons
<b>HDRATE</b>	F	19	HD update rate for historical values (in sec, one decimal possible)
<b>HDTIEFE</b>	N	7	HD entry depth for historical values (number)
<b>NACHSORT</b>	R	1	HD data as postsorted values
<b>DRRATE</b>	F	19	Updating to the output (for zenon DDE server, in [s], one decimal possible)
<b>HYST_PLUS</b>	F	16	Positive hysteresis, from measuring range
<b>HYST_MINUS</b>	F	16	Negative hysteresis, from measuring range
<b>PRIOR</b>	N	16	Priority of the variable
<b>REAMATRIZE</b>	C	32	Allocated reaction matrix
<b>ERSATZWERT</b>	F	16	Substitute value, from measuring range
<b>SOLLMIN</b>	F	16	Minimum for set value actions, from measuring range
<b>SOLLMAX</b>	F	16	Maximum for set value actions, from measuring range
<b>VOMSTANDBY</b>	R	1	Get value from standby server; the value of the variable is not requested from the server but from the Standby Server in redundant networks



Identification	Type	Field size	Comment
RESOURCE	C	128	Resources label. Free string for export and display in lists.  The length can be limited using the MAX_LAENGE entry in <b>project.ini</b> .
ADJWVBA	R	1	Non-linear value adaption: 0: Non-linear value adaption is used 1: Non-linear value adaption is not used
ADJZENON	C	128	Linked VBA macro for reading the variable value for non-linear value adjustment.
ADJWVBA	C	128	ed VBA macro for writing the variable value for non-linear value adjustment.
ZWREMA	N	16	Linked counter REMA.
MAXGRAD	N	16	Gradient overflow for counter REMA.



### Attention

When importing, the driver object type and data type must be amended to the target driver in the DBF file in order for variables to be imported.

## LIMIT VALUE DEFINITION

Limit definition for limit values 1 to 4, or status 1 to 4:

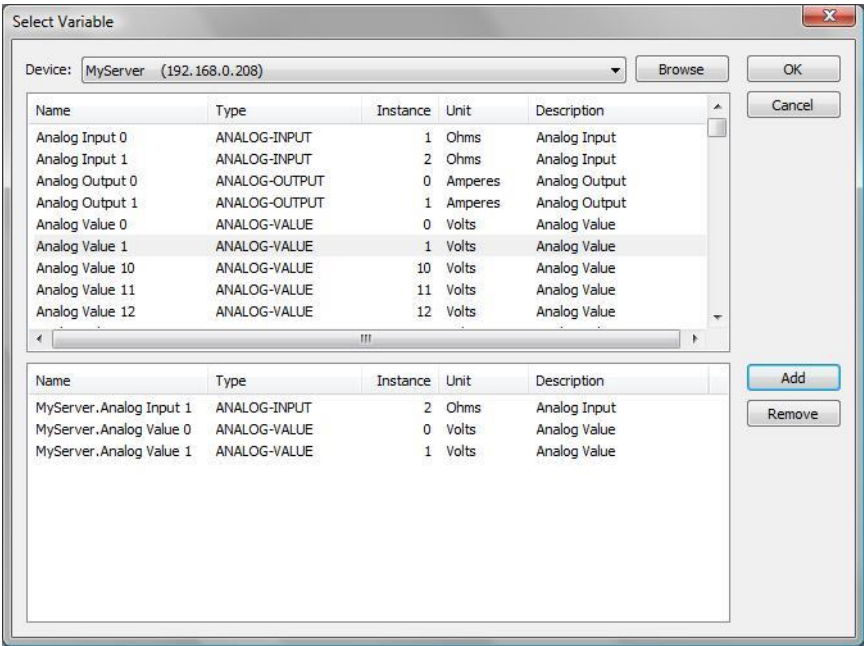
Identification	Type	Field size	Comment
AKTIV1	R	1	Limit value active (per limit value available)
GRENZWERT1	F	20	technical value or ID number of a linked variable for a dynamic limit value (see VARIABLEx) (if VARIABLEx is 1 and here it is -1, the existing variable linkage is not overwritten)
SCHWWERT1	F	16	Threshold value for limit value
HYSTERESE1	F	14	Is not used
BLINKEN1	R	1	Set blink attribute

Identification	Type	Field size	Comment
<b>BTB1</b>	R	1	Logging in CEL
<b>ALARM1</b>	R	1	Alarm
<b>DRUCKEN1</b>	R	1	Printer output (for CEL or Alarm)
<b>QUITTIER1</b>	R	1	Must be acknowledged
<b>LOESCHE1</b>	R	1	Must be deleted
<b>VARIABLE1</b>	R	1	Dyn. limit value linking the limit is defined by an absolute value (see field GRENZWERTx).
<b>FUNC1</b>	R	1	Functions linking
<b>ASK_FUNC1</b>	R	1	Execution via Alarm Message List
<b>FUNC_NR1</b>	N	10	ID number of the linked function (if "-1" is entered here, the existing function is not overwritten during import)
<b>A_GRUPPE1</b>	N	10	Alarm/Event Group
<b>A_KLASSE1</b>	N	10	Alarm/Event Class
<b>MIN_MAX1</b>	C	3	Minimum, Maximum
<b>FARBE1</b>	N	10	Color as Windows coding
<b>GRENZTXT1</b>	C	66	Limit value text
<b>A_DELAY1</b>	N	10	Time delay
<b>INVISIBLE1</b>	R	1	Invisible

Expressions in the column "Comment" refer to the expressions used in the dialog boxes for the definition of variables. For more information, see chapter Variable definition.

### 7.4.3 Online import

Variables are created with the driver online import. You can find the command in the context menu of the driver in the driver list.



Parameter	Description
Device	Select the device to be browsed
Button "Browse"	Reads out the variables of the device
Button "Add"	Adds the selected variable to the selection
Button "Remove"	Removes the selected variable from the selection
Button "OK"	Adds the selected variables to the variable list
Button "Cancel"	Cancel the import

### 7.5 Communication details (Driver variables)

The driver kit implements a number of driver variables. This variables are part of the driver object type *Communication details*. These are divided into:

- ▶ Information
- ▶ Configuration
- ▶ Statistics and
- ▶ Error message

The definitions of the variables implemented in the driver kit are available in the import file **DRVVAR.DBF** and can be imported from there.

Path to file: %ProgramData%\COPA-DATA\zenon<Versionsnummer>\PredefinedVariables

**Note:** Variable names must be unique in zenon. If driver variables of the driver object type *Communication details* are to be imported from **DRVVAR.DBF** again, the variables that were imported beforehand must be renamed.



### Information

Not every driver supports all driver variables of the driver object type *Communication details*.

For example:

- ▶ Variables for modem information are only supported by modem-compatible drivers.
- ▶ Driver variables for the polling cycle are only available for pure polling drivers.
- ▶ Connection-related information such as **ErrorMSG** is only supported for drivers that only edit one connection at a time.

## INFORMATION

Name from import	Type	Offset	Description
MainVersion	UINT	0	Main version number of the driver.
SubVersion	UINT	1	Sub version number of the driver.
BuildVersion	UINT	29	Build version number of the driver.
RTMajor	UINT	49	zenon main version number
RTMinor	UINT	50	zenon sub version number
RTSp	UINT	51	zenon Service Pack number
RTBuild	UINT	52	zenon build number
LineStatIdle	BOOL	24.0	TRUE, if the modem connection is idle
LineStateOffering	BOOL	24.1	TRUE, if a call is received
LineStateAccepted	BOOL	24.2	The call is accepted
LineStateDialtone	BOOL	24.3	Dialtone recognized
LineStateDialing	BOOL	24.4	Dialing active

Name from import	Type	Offset	Description
LineStateRingBack	BOOL	24.5	While establishing the connection
LineStateBusy	BOOL	24.6	Target station is busy
LineStateSpecialInfo	BOOL	24.7	Special status information received
LineStateConnected	BOOL	24.8	Connection established
LineStateProceeding	BOOL	24.9	Dialing completed
LineStateOnHold	BOOL	24.10	Connection in hold
LineStateConferenced	BOOL	24.11	Connection in conference mode.
LineStateOnHoldPendConf	BOOL	24.12	Connection in hold for conference
LineStateOnHoldPendTransfer	BOOL	24.13	Connection in hold for transfer
LineStateDisconnected	BOOL	24.14	Connection terminated.
LineStateUnknow	BOOL	24.15	Connection status unknown
ModemStatus	UDINT	24	Current modem status
TreiberStop	BOOL	28	Driver stopped  For <i>driver stop</i> , the variable has the value <i>TRUE</i> and an <b>OFF</b> bit. After the driver has started, the variable has the value <i>FALSE</i> and no <b>OFF</b> bit.
SimulRTState	UDINT	60	Informs the status of Runtime for driver simulation.
ConnectionStates	STRING	61	Internal connection status of the driver to the PLC.  Connection statuses:  0: Connection OK 1: Connection failure 2: Connection simulated  Formating:  <Netzadresse>:<Verbindungszustand>;...;;

Name from import	Type	Offset	Description
			<p>A connection is only known after a variable has first signed in. In order for a connection to be contained in a string, a variable of this connection must be signed in once.</p> <p>The status of a connection is only updated if a variable of the connection is signed in. Otherwise there is no communication with the corresponding controller.</p>

## CONFIGURATION

Name from import	Type	Offset	Description
ReconnectInRead	<i>BOOL</i>	27	If TRUE, the modem is automatically reconnected for reading
ApplyCom	<i>BOOL</i>	36	Apply changes in the settings of the serial interface. Writing to this variable immediately results in the method SrvDrvVarApplyCom being called (which currently has no further function).
ApplyModem	<i>BOOL</i>	37	Apply changes in the settings of the modem. Writing this variable immediately calls the method SrvDrvVarApplyModem. This closes the current connection and opens a new one according to the settings <b>PhoneNumberSet</b> and <b>ModemHwAdrSet</b> .
PhoneNumberSet	<i>STRING</i>	38	Telephone number, that should be used
ModemHwAdrSet	<i>DINT</i>	39	Hardware address for the telephone number
GlobalUpdate	<i>UDINT</i>	3	Update time in milliseconds (ms).
BGlobalUpdaten	<i>BOOL</i>	4	TRUE, if update time is global
TreiberSimul	<i>BOOL</i>	5	TRUE, if driver in sin simulation mode
TreiberProzab	<i>BOOL</i>	6	TRUE, if the variables update list should be kept in the memory
ModemActive	<i>BOOL</i>	7	TRUE, if the modem is active for the driver

Name from import	Type	Offset	Description
Device	<i>STRING</i>	8	Name of the serial interface or name of the modem
ComPort	<i>UINT</i>	9	Number of the serial interface.
Baudrate	<i>UDINT</i>	10	Baud rate of the serial interface.
Parity	<i>SINT</i>	11	Parity of the serial interface
ByteSize	<i>USINT</i>	14	Number of bits per character of the serial interface  Value = 0 if the driver cannot establish any serial connection.
StopBit	<i>USINT</i>	13	Number of stop bits of the serial interface.
Autoconnect	<i>BOOL</i>	16	TRUE, if the modem connection should be established automatically for reading/writing
PhoneNumber	<i>STRING</i>	17	Current telephone number
ModemHwAdr	<i>DINT</i>	21	Hardware address of current telephone number
RxIdleTime	<i>UINT</i>	18	Modem is disconnected, if no data transfer occurs for this time in seconds (s)
WriteTimeout	<i>UDINT</i>	19	Maximum write duration for a modem connection in milliseconds (ms).
RingCountSet	<i>UDINT</i>	20	Number of ringing tones before a call is accepted
ReCallIdleTime	<i>UINT</i>	53	Waiting time between calls in seconds (s).
ConnectTimeout	<i>UINT</i>	54	Time in seconds (s) to establish a connection.

## STATISTICS

Name from import	Type	Offset	Description
MaxWriteTime	<i>UDINT</i>	31	The longest time in milliseconds (ms) that is required for writing.

Name from import	Type	Offset	Description
MinWriteTime	UDINT	32	The shortest time in milliseconds (ms) that is required for writing.
MaxBlkReadTime	UDINT	40	Longest time in milliseconds (ms) that is required to read a data block.
MinBlkReadTime	UDINT	41	Shortest time in milliseconds (ms) that is required to read a data block.
WriteErrorCount	UDINT	33	Number of writing errors
ReadSucceedCount	UDINT	35	Number of successful reading attempts
MaxCycleTime	UDINT	22	Longest time in milliseconds (ms) required to read all requested data.
MinCycleTime	UDINT	23	Shortest time in milliseconds (ms) required to read all requested data.
WriteCount	UDINT	26	Number of writing attempts
ReadErrorCount	UDINT	34	Number of reading errors
MaxUpdateTimeNormal	UDINT	56	Time since the last update of the priority group <b>Normal</b> in milliseconds (ms).
MaxUpdateTimeHigher	UDINT	57	Time since the last update of the priority group <b>Higher</b> in milliseconds (ms).
MaxUpdateTimeHigh	UDINT	58	Time since the last update of the priority group <b>High</b> in milliseconds (ms).
MaxUpdateTimeHighest	UDINT	59	Time since the last update of the priority group <b>Highest</b> in milliseconds (ms).
PokeFinish	BOOL	55	Goes to 1 for a query, if all current pokes were executed

## ERROR MESSAGE

Name from import	Type	Offset	Description
ErrorTimeDW	UDINT	2	Time (in seconds since 1.1.1970), when the last error occurred.



Name from import	Type	Offset	Description
ErrorTimeS	STRING	2	Time (in seconds since 1.1.1970), when the last error occurred.
RdErrPrimObj	UDINT	42	Number of the PrimObject, when the last reading error occurred.
RdErrStationsName	STRING	43	Name of the station, when the last reading error occurred.
RdErrBlockCount	UINT	44	Number of blocks to read when the last reading error occurred.
RdErrHwAdresse	DINT	45	Hardware address when the last reading error occurred.
RdErrDatablockNo	UDINT	46	Block number when the last reading error occurred.
RdErrMarkerNo	UDINT	47	Marker number when the last reading error occurred.
RdErrSize	UDINT	48	Block size when the last reading error occurred.
DrvError	USINT	25	Error message as number
DrvErrorMsg	STRING	30	Error message as text
ErrorFile	STRING	15	Name of error log file

## 8 Driver-specific functions

The driver supports the following functions:

### PROTOCOL

The protocol was defined by the ASHRAE (American Society of Heating, Refrigeration and Air-Conditioning Engineers, Inc.) and is described extensively in the ASHRAE standard 135-2001 + Appendix A – L "A Data Communication Protocol for Building Automation and Control Networks".

## CONNECTION

The BACnet standard offers five options on the data link and physical layers of the OSI layer model (which is reduced to four layers). The driver only supports the option ISO 8802-3, known as "Ethernet". This option (together with the other layers of the BACnet protocol) is also called "BACnet/IP, Annex J".

BACnet Layers				
BACnet Application Layer				
BACnet Network Layer				
ISO 8802-2 Type1		MS/TP	PTP	LonTalk
ISO 8802-3	ARCNET	EIA-485 (RS485)	EIA-232 (RS232)	

The communication of this option is based on ISO 8802-2 Type1 (Ethernet) in the data link layer. This means that the PC requires an Ethernet card with connection to a TCP/IP network.

## DEFINITION

Term	Description
<b>BAS</b>	BACnet automation station
<b>BAZ</b>	Command output time
<b>COV</b>	Change of Value
<b>DA</b>	Data type
<b>DCS</b>	Double Command State for TK 46
<b>KT</b>	Channel type
<b>OB</b>	Object
<b>RPM</b>	ReadPropertyMultiple

## GENERAL FUNCTION DESCRIPTION

The BACnet automation station (BAS) is represented as a Device-Object in the BACnet driver. The BAS behaves as a server. For the peer-to-peer data exchange the BACnet driver connects as a client. Each datapoint of the BAS is modeled as a BACnet object. For the data update the COV Subscription as well as the ReadPropertyMultiple (RPM) service can be used. The cycle time for the resubscription as well as the polling interval for the RPM service can be defined in four priority groups (see Configuration of the BACnet driver).

A time synchronization from the BACnet driver in the direction of BAS can be defined.

## ESTABLISHING CONNECTION AND EXCHANGING DATA

As a client the BACnet driver sends the "Who-Is" service to the subnet mask as a broadcast. The existing BAS answers with an "I-Am". The driver variable of the type "Component status" resembling the name of the device object is set to 0 (OK).

With the service "Who-Has(object\_name)" the client gets the BACnet objects of the according server. With the service "I-Have" the server sends the objects (incl. the properties "object\_instance" and "object\_type") to the client. Unanswered "Who-Has" services are repeated according to the defined number of retries. If there are BACnet objects that still do not answer with the "I-Have" service, the component status of the according BAS is set to 1 (initializing error). The corresponding object names are written into the log file.

The client then starts the COV subscriptions or RPM services for the existing objects. If the value (present\_value) or the status (status\_flags) of a COV object changes, the client is informed with a COV notification. Then it requests the time stamp (event\_time\_stamps) for the according object from the server with the ReadProperty service. With the RPM services the properties Present\_Value, Status\_Flags and Event\_Time\_Stamps are cyclically requested from the server.

Send data (Present\_Value, Status\_Flags, Event\_Time\_Stamps) are sent to the server with the WritePropertyMultiple service. If one of these properties cannot be written on the server, the server acknowledges this with an error message („Rec\_error: WritePropertyMultiple").

## SAVING VALUE AND STATUS

Values, stati and time stamps of the output variables are saved spontaneously. So a data loss in the case of a computer breakdown is avoided. The saved information is read on a restart.

## BREAKDOWN MONITORING

In order to check the presence of the server the client cyclically sends "Who-Is" telegrams. The cycle time is defined in the driver configuration dialog under BACnet settings.

If the server does not answer with an "I-Am" within a certain time, the interface will be considered as not operative. The corresponding virtual datapoint of the type BACnet component status is set to 64 (NOK). All process datapoints of this BAS are set to disturbed (invalid).

The server announces the reestablishment of the connection with an "I-Am". The further procedure is the same as the one with the connection establishment.

## ACCESS METHODS

The values of the variables can be read spontaneous or by polling. The type of polling can be selected via the property "priority" of the individual variables

If the hardware allows the reading of time stamps, the variables get these time stamps, otherwise the variables get the time stamps from the driver.

<b>Polling</b>	<b>If the variable property "Priority" is set to "Higher", "High" or "Highest", the variable values will be polled in the interval defined for the according priority in the driver configuration (page "General"). For this, the BACnet service ReadPropertyMulti (reads the object properties "present_value", "status_flags" and "event_time_stamps") is used.</b>
<b>Spontaneous</b>	<p>If the variable property "Priority" is set to "Normal", the variable values will be read with the BACnet service COV ("change of value"). After the first request of the variable value, a so-called "COV subscription" will be executed, i.e. the according object will be asked to send a COV notification telegram each time the value changes.</p> <p>The COV subscription is valid for the time defined for the priority "Normal" in the driver configuration. After that time the device will stop sending value changes. If in this case the variable value is still needed, the driver will execute another COV subscription.</p>

After receiving the COV notification of BACnet objects, the properties "present\_value" and "status\_flags" (FAULT <=> IBit) are read and "event\_time\_stamps" is requested with the service ReadProperty. If the received time is invalid (0 or 255), the BACnet driver will use the current computer time.

## TAKING BACK VALUES FROM THE PRIORITY ARRAY:

For some object types, you can remove values set by zenon from the BACnet priority array of the variable on the PLC. However, this cannot be achieved directly via the driver; you will need a VBA script for this.

Example for a VBA script:

```
Sub ResetPrioArray()  
    Dim Var As Variable  
    Set Var = Variables.Item("TestVar 0")  
    Var.SetValueWithStatus 0, 262144, 0, 0    '262144 = Hex 40000, corresponds to the set  
INVALID bit  
End Sub
```

## LIMITATIONS

If you launch the driver several times, you will need different UDP ports for every driver. These ports also have to be configurable on the PLCs (BACNet Server).

Priority: The driver sends set values with priority 8

## 9 Driver command function

The zenon **Driver commands** function is to influence drivers using zenon. You can do the following with a driver command:

- ▶ Start
- ▶ Stop
- ▶ Shift a certain driver mode
- ▶ Instigate certain actions

**Note:** This chapter describes standard functions that are valid for most zenon drivers. Not all functions described here are available for every driver. For example, a driver that does not, according to the data sheet, support a modem connection also does not have any modem functions.



### Attention

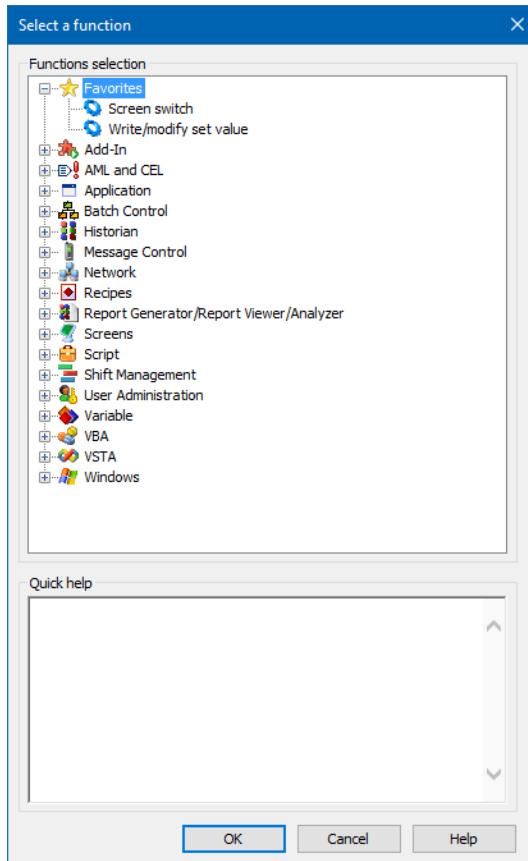
The zenon **Driver commands** function is not identical to driver commands that can be executed in the Runtime with Energy drivers!

## CONFIGURATION OF THE FUNCTION

Configuration is carried out using the **Driver commands** function.  
To configure the function:

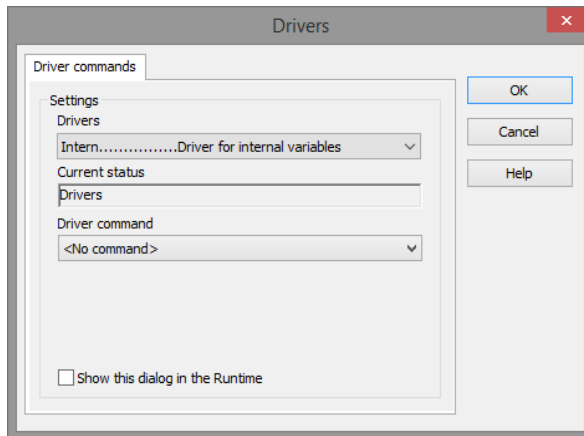
1. Create a new function in the zenon Editor.

The dialog for selecting a function is opened



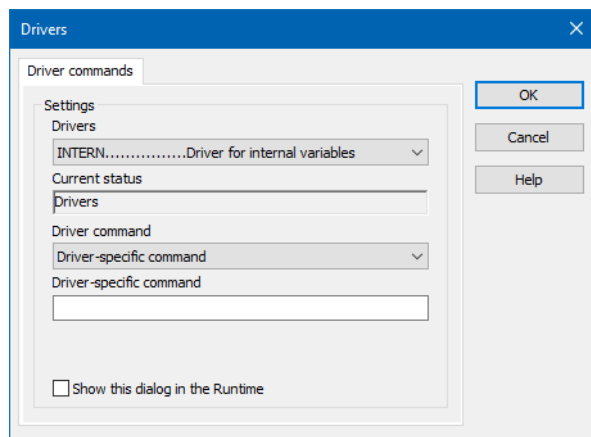
2. Navigate to the node **Variable**.
3. Select the **Driver commands** entry.

The dialog for configuration is opened



4. Select the desired driver and the required command.
5. Close the dialog by clicking on **OK** and ensure that the function is executed in the Runtime. Heed the notices in the **Driver command function in the network** section.

## DRIVER COMMAND DIALOG



Option	Description
<b>Driver</b>	Selection of the driver from the drop-down list. It contains all drivers loaded in the project.
<b>Current condition</b>	Fixed entry that is set by the system. Has no function in the current version.
<b>Driver command</b>	Selection of the desired driver command from a drop-down list.  For details on the configurable driver commands, see the <b>available driver commands</b> section.
<b>Driver-specific command</b>	Entry of a command specific to the selected driver.

Option	Description
	<b>Note:</b> Only available if, for the <b>driver command</b> option, the <i>driver-specific command</i> has been selected.
<b>Show this dialog in the Runtime</b>	<p>Configuration of whether the configuration can be changed in the Runtime:</p> <ul style="list-style-type: none"> <li>▶ <i>Active:</i> This dialog is opened in the Runtime before executing the function. The configuration can thus still be changed in the Runtime before execution.</li> <li>▶ <i>Inactive:</i> The Editor configuration is applied in the Runtime when executing the function.</li> </ul> <p>Default: <i>inactive</i></p>

## CLOSE DIALOG

Options	Description
OK	<b>Applies settings and closes the dialog.</b>
Cancel	Discards all changes and closes the dialog.
Help	Opens online help.

## AVAILABLE DRIVER COMMANDS

These driver commands are available - depending on the selected driver:

Driver command	Description
<No command>	<p>No command is sent.</p> <p>A command that already exists can thus be removed from a configured function.</p>
<i>Start driver (online mode)</i>	<p>Driver is reinitialized and started.</p> <p><b>Note:</b> If the driver has already been started, it must be stopped. Only then can the driver be re-initialized and started.</p>
<i>Stop driver (offline mode)</i>	<p>Driver is stopped. No new data is accepted.</p> <p><b>Note:</b> If the driver is in offline mode, all variables that were created for this driver receive the status <i>switched off</i> (OFF; Bit 20).</p>



Driver command	Description
<i>Driver in simulation mode</i>	Driver is set into simulation mode. The values of all variables of the driver are simulated by the driver. No values from the connected hardware (e.g. PLC, bus system, ...) are displayed.
<i>Driver in hardware mode</i>	Driver is set into hardware mode. For the variables of the driver the values from the connected hardware (e.g. PLC, bus system, ...) are displayed.
<i>Driver-specific command</i>	Entry of a driver-specific command. Opens input field in order to enter a command.
<i>Activate driver write set value</i>	Write set value to a driver is possible.
<i>Deactivate driver write set value</i>	Write set value to a driver is prohibited.
<i>Establish connection with modem</i>	Establish connection (for modem drivers)  Opens the input fields for the hardware address and for the telephone number.
<i>Disconnect from modem</i>	Terminate connection (for modem drivers)
<i>Driver in counting simulation mode</i>	Driver is set into counting simulation mode. All values are initialized with 0 and incremented in the set update time by 1 each time up to the maximum value and then start at 0 again.
<i>Driver in static simulation mode</i>	No communication to the controller is established. All values are initialized with 0.
<i>Driver in programmed simulation mode</i>	The values are calculated by a freely-programmable simulation project. The simulation project is created with the help of the zenon Logic Workbench and runs in the zenon Logic Runtime.

## DRIVER COMMAND FUNCTION IN THE NETWORK

If the computer on which the **Driver commands** function is executed is part of the zenon network, further actions are also carried out:

- ▶ A special network command is sent from the computer to the project server. It then executes the desired action on its driver.
- ▶ In addition, the Server sends the same driver command to the project standby. The standby also carries out the action on its driver.

This makes sure that Server and Standby are synchronized. This only works if the Server and the Standby both have a working and independent connection to the hardware.

## 10 Error analysis

Should there be communication problems, this chapter will assist you in finding out the error.

### 10.1 Error analysis

#### LOGGING

You can choose to log the entire telegram traffic between the BACnet driver and the BAS (see BACnet32\_DiagnosticSetting (on page 18)).

Data is stored in the file `<runtimepath>\RT\FILES\zenon\custom\drivers\BACnet.log`

For Editor communication (browsing), the following file is used:  
`<SQLpath>\<ProjektGUID>\FILES\zenon\custom\drivers\BACnet.log`.

### 10.2 Analysis tool

All zenon modules such as Editor, Runtime, drivers, etc. write messages to a joint log file. To display them correctly and clearly, use the Diagnosis Viewer (main.chm::/12464.htm) program that was also installed with zenon. You can find it under **Start/All programs/zenon/Tools 8.10 -> Diagviewer**.

zenon driver log all errors in the LOG files. LOG files are text files with a special structure. The default folder for the LOG files is subfolder **LOG** in the folder **ProgramData**. For example:

**%ProgramData%\COPA-DATA\LOG.**

**Attention:** With the default settings, a driver only logs error information. With the Diagnosis Viewer you can enhance the diagnosis level for most of the drivers to "Debug" and "Deep Debug". With this the driver also logs all other important tasks and events.

In the Diagnosis Viewer you can also:

- ▶ Follow newly-created entries in real time
- ▶ customize the logging settings
- ▶ change the folder in which the LOG files are saved

#### Note:

1. The Diagnosis Viewer displays all entries in UTC (coordinated world time) and not in local time.

2. The Diagnosis Viewer does not display all columns of a LOG file per default. To display more columns activate property **Add all columns with entry** in the context menu of the column header.
3. If you only use **Error-Logging**, the problem description is in the column **Error text**. For other diagnosis level the description is in the column **General text**.
4. For communication problems many drivers also log error numbers which the PLC assigns to them. They are displayed in **Error text** or **Error code** or **Driver error parameter (1 and 2)**. Hints on the meaning of error codes can be found in the driver documentation and the protocol/PLC description.
5. At the end of your test set back the diagnosis level from **Debug** or **Deep Debug**. At **Debug** and **Deep Debug** there are a great deal of data for logging which are saved to the hard drive and which can influence your system performance. They are still logged even after you close the Diagnosis Viewer.



### Attention

In Windows CE errors are not logged per default due to performance reasons.

You can find further information on the Diagnosis Viewer in the Diagnose Viewer (main.chm::/12464.htm) manual.

## 10.3 Check list

Is the PLC connected to the power supply
Are the participants available in the TCP/IP network
Can the PLC be reached via the PING command
Can the PLC be reached via TELNET
Are the PLC and the PLC connected with the right cable
Did you select the right COM port
Do the communication parameters match (Baud rate, parity, start/stop bits,...)
Is the COM port blocked by another application
Did you configure the net address correctly, both in the driver dialog and in the address properties of the variable
Did you use the right object type for the variable
Does the offset addressing of the variable match the one in the PLC
Use the DiagViewer for further analysis -> Which messages does it show

## 11 PICS (Protocol Implementation Conformance Statement)

Date	September 21, 2005
Vendor Name	COPA-DATA GmbH
Product Name	BACnet-driver for process control system (HMI/SCADA)
Product Model Number:	Version 6.20 SP1
Applications Software Version	6.20.1
BACnet protocol Revision	2

### PRODUCT DESCRIPTION

The BACnet driver allows communication and data exchange between one or more BACnet-capable devices and the SCADA-Runtime. Therefore it's required that the connected BACnet devices are operating as servers. In the BACnet driver only the Client functionality is implemented.

### BACNET STANDARDIZED DEVICE PROFILE (ANNEX L):

X	BACnet Operator Workstation (B-OWS)
	BACnet Building Controller (B-BC)
	BACnet Advanced Application Controller (B-AAC)
	BACnet Application Specific Controller (B-ASC)
	BACnet Smart Sensor (B-SS)
	BACnet Smart Actuator (B-SA)

### ADDITIONAL BACNET INTEROPERABILITY BUILDING BLOCKS SUPPORTED (ANNEX K):

DS-RP-A, DS-RPM-A, DS-WP-A, DS-WPM-A, DS-COV-A, DM-DDB-A, DM-DOB-A, DM-TS-A, DM-UTC-A, SCHED-A

## SEGMENTATION CAPABILITY:

	Segmented requests supported	Window Size _____
	Segmented responses supported	Window Size _____

## STANDARD OBJECT TYPES SUPPORTED:

Analog-Input, Analog-Output, Binary-Input, Binary-Output, Multi-State-Input, Multi-State-Output, Schedule, Device

## OBJECT DEFINITIONS

### 1. ANALOG INPUT

Property	Client uses
Present_Value	R
Status_Flags	R
Event_Time_Stamps	R

### 2. ANALOG OUTPUT

Property	Client uses
Present_Value	W
Status_Flags	W
Event_Time_Stamps	W

### 3. ANALOG VALUE

Property	Client uses
Present_Value	R / W
Status_Flags	R / W
Event_Time_Stamps	R / W

### 4. BINARY INPUT

Property	Client uses
Present_Value	R

Property	Client uses
Status_Flags	R
Event_Time_Stamps	R

## 5. BINARY OUTPUT

Property	Client uses
Present_Value	W
Status_Flags	W
Event_Time_Stamps	W

## 6. BINARY VALUE

Property	Client uses
Present_Value	R / W
Status_Flags	R / W
Event_Time_Stamps	R / W

## 7. MULTI STATE INPUT

Property	Client uses
Present_Value	R
Status_Flags	R
Event_Time_Stamps	R

## 8. MULTI STATE OUTPUT

Property	Client uses
Present_Value	R
Status_Flags	R
Event_Time_Stamps	R

## 9. MULTI STATE VALUE

Property	Client uses
Present_Value	R / W
Status_Flags	R / W
Event_Time_Stamps	R / W

## 10. SCHEDULE

Property	Client uses
Effective_Period	R / W (as String)
Weekly_Schedule	R / W (as String)
Exception_Schedule	R / W (as String)

## 11. DEVICE

Property	Client uses
Local_Date	W
Local_Time	W

## DATA LINK LAYER

X	BACnet/IP, (Annex J)
	BACnet/IP, (Annex J), Foreign Device
	ISO 8802-2, Ethernet (Clause 7)
	ASTM 878.1, 2.5Mb. ARCNET (Clause 8)
	ASTM 878.1, RS485 ARCNET (Clause 8), baud rate(s): _____
	MS/TP master (Clause 9), baud rate(s): _____
	MS/TP slave (Clause 9), baud rate(s): _____
	Point-To-Point, EIA 232 (Clause 10), baud rate(s): _____
	Point-To-Point, modem (Clause 10), baud rate(s): _____

<b>X</b>	<b>BACnet/IP, (Annex J)</b>
	LonTalk, (Clause 11), medium: _____
	Other

## NETWORKING OPTIONS

	<b>Router, Clause 6 - Routing configurations:</b>
	Annex H, BACnet Tunneling Router over IP
	BACnet/IP Broadcast Management Device (BBMD)

## CHARACTER SETS SUPPORTED

<b>X</b>	<b>ANSI X3.4</b>
	IBM /Microsoft DBCS
	ISO 8859-1
	ISO 10646 (ICS-4)
	ISO 10646 (UCS2)
	JIS C 6226

## OPTIONAL SERVICE-PARAMETERS SUPPORTED

ReadProperty, ReadPropertyMultiple, WriteProperty, WritePropertyMultiple, SubscribeCOV, COVNotification, Who-Is, I-Am, Who-Has, I-Have, TimeSynchronization, TimeUTCSynchronization